

# Quasi-static evolution and congested transport

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# Hard congestion in crowd motion

The following crowd motion model is proposed by Maury, Roundneff-Chupin and Santambrogio (2010):

- $\rho(x, t)$ : pedestrian population density, which cannot exceed a certain maximal value (which we assume to be 1).
- $-\nabla\Phi(x)$ : The desired velocity field for an individual located at  $x$ . It may not be achieved due to the constraint  $\|\rho(\cdot, t)\|_\infty \leq 1$ .
- In the saturated zone  $\{\rho(\cdot, t) = 1\}$ , the actual velocity field  $\mathbf{v}(\cdot, t)$  must satisfy  $\nabla \cdot \mathbf{v}(\cdot, t) \geq 0$ , in order to not increase the density. (If so, we say  $\mathbf{v}$  is *feasible*).

# Hard congestion in crowd motion

- In [MRS], they consider the PDE system

$$(P) \quad \begin{cases} \rho_t + \nabla \cdot (\rho \mathbf{v}) = 0 \\ \mathbf{v}(\cdot, t) = -P_{C_\rho} \nabla \Phi, \end{cases}$$

where  $P_{C_\rho}$  is the projection towards the space of feasible velocity fields in  $L^2$  sense.

- They link this system with the following gradient flow: For  $\rho \in \mathcal{P}_2(\mathbb{R}^d)$ , let

$$E_\infty[\rho] = \begin{cases} \int_{\mathbb{R}^d} \rho(x) \Phi(x) dx & \|\rho\|_\infty \leq 1 \\ +\infty & \text{otherwise.} \end{cases}$$

# Gradient flow approach for hard congestion

- Let  $\rho_\infty(\cdot, t)$  be the gradient flow of  $E_\infty$  with respect to Wasserstein distance  $W_2$  with initial data  $\rho_0$ . Existence and uniqueness of  $\rho_\infty$  can be shown following the book by Ambrosio, Gigli and Savaré (2005).
- [MRSV] showed that  $\rho_\infty$  is a weak solution to (P), however uniqueness of the weak solution to (P) is unknown since the velocity field  $v = -P_{C\rho} \nabla \Phi$  is only in  $L^2$ .
- Let  $\Delta \Phi \geq 0$ . Then formally speaking, the velocity field pulls the particles together. In this setting we will show a unique characterization of the velocity field  $v$  for  $\rho_\infty$ .

# Modification of the velocity

We expect the modified velocity to be of the form  $v = \nabla p + \nabla \Phi$ .  
The continuity equation for  $\rho$  then is expected to be of the form

$$\rho_t - \nabla \cdot (\rho(\nabla p + \nabla \Phi)) = 0,$$

where  $p$  is the pressure generated by the constraint, supported on the congested set  $\{\rho = 1\}$ .

## A remark on the assumption $\Delta\Phi \geq 0$

When  $\Delta\Phi \geq 0$ , we expect the pressure to be nonzero in all of  $\{\rho = 1\}$ . Moreover the modified velocity should be incompressible in the congested region since the original velocity field only tries to compress the density. Thus  $p$  should solve

$$\nabla \cdot (\nabla p + \nabla\Phi) = 0 \text{ or } -\Delta p = \Delta\Phi \text{ in } \{\rho = 1\}.$$

# Evolution of the congested region

Suppose  $\rho$  solves the modified discontinuity equation with  $\nabla \rho$  discontinuously changing to zero across  $\partial\Omega(t)$ . Then denoting  $\rho = \rho^I \chi_{\Omega(t)} + \rho^O$  we have

$$\begin{aligned} 0 &= \partial_t [\int_{\Omega(t)} (\rho^I)_t dx + \int_{\mathbb{R}^n - \Omega(t)} \rho^O dx] \\ &= \int_{\Omega(t)} (\rho^I)_t + \int_{\mathbb{R}^n - \Omega(t)} (\rho^O)_t dx + \int_{\partial\Omega(t)} V(\rho^I - \rho^O) dS \\ &= \int_{\Omega(t)} \nabla \cdot (\rho^I(\nabla \rho + \nabla \Phi)) + \int_{\Omega(t)^c} \nabla \cdot (\rho^O \nabla \Phi) + \int_{\partial\Omega(t)} V(\rho^I - \rho^O) \\ &= \int_{\partial\Omega(t)} \rho^I \partial_\nu \rho + (\rho^I - \rho^O)(\partial_\nu \Phi + V) dS, \end{aligned}$$

where  $V = V_{x,t}$  denotes the (outward) normal velocity of  $\Omega(t)$ .

# Evolution of $\rho$ when $\Delta\Phi \geq 0$

Above calculation suggests the following evolution for

$\rho(\cdot, t) = \chi_{\Omega_t} + \rho^0$ , where the congested set  $\Omega(t) := \{p(\cdot, t) > 0\}$  is determined by the following free boundary problem for  $p \geq 0$ :

$$\begin{cases} -\Delta p(\cdot, t) = \Delta\Phi & \text{in } \{p(\cdot, t) > 0\}; \\ V = \frac{1}{(1-\rho^0)}(-\partial_\nu p) - \partial_\nu \Phi & \text{on } \partial\{p(\cdot, t) > 0\}. \end{cases}$$



- Note that the velocity law

$$V = \frac{1}{1 - \rho\sigma} |Dp| - \partial_\nu \Phi$$

indicates that there is a generic discontinuity of  $\rho$  across  $\partial\Omega(t)$ .

- The well-posedness of the free boundary problem can be shown by viscosity solutions theory.
- We are interested in connecting this problem with the gradient flow solution  $\rho_\infty$ . In addition to the assumption  $\Delta\Phi \geq 0$ , we will also assume that the initial data is patch.

# Quasi-static evolution: patch case

Suppose  $\rho_0 = \chi_{\Omega_0}$ , and consider the following free boundary problem that  $p$  solves with the initial data  $\{p(\cdot, 0) > 0\} = \Omega_0$ :

$$(FB) \quad \begin{cases} -\Delta p(\cdot, t) = \Delta \Phi & \text{in } \{p(\cdot, t) > 0\} =: \Omega_t; \\ V = |Dp| - \partial_\nu \Phi & \text{on } \partial\Omega_t. \end{cases}$$

Our goal is to prove that the gradient flow solution  $\rho_\infty$  with initial data  $\rho_0$  satisfies  $\rho_\infty(\cdot, t) = \chi_{\Omega_t}$ .

# Approximation by Porous Medium Equation

- Let  $\rho_m$  solve the following porous medium equation with drift:

$$\rho_t = \Delta \rho^m + \nabla \cdot (\rho \nabla \Phi),$$

with initial data  $\rho(\cdot, 0) = \chi_{\Omega_0}$ .

- It is well known (Otto, 2001) that  $\rho_m$  is the gradient flow for

$$E_m[\rho] = \frac{1}{m} \int \rho^m dx + \int \rho \Phi dx.$$

- We will show that  $\rho_m$  converging to  $\rho_\infty$  as  $m \rightarrow \infty$ , with a rate.
- We will also show that  $\rho_m$  converges to  $\chi_{\Omega_t}$ , yielding the desired statement,  $\rho_\infty = \chi_{\Omega_t}$ .

## Theorem (Alexander-K-Yao., 2013)

Let  $\Omega_0$  be a compact set in  $\mathbb{R}^d$  with locally Lipschitz boundary, then

- (a) Assuming  $\Delta\Phi \geq 0$ . Then there is a unique family of compact sets  $\Omega_t$  evolving with (FB). As  $m \rightarrow \infty$ ,  $\rho_m \rightarrow \chi_{\Omega_t}$  locally uniformly away from  $\partial\Omega(t)$ .
- (b) Assume  $\|D^2\Phi\|_\infty \leq \infty$  and  $\inf\Phi$  is finite. Then  $\rho_m(\cdot, t)$  converges to  $\rho_\infty(\cdot, t)$  in  $W_2$  distance uniformly in  $t \in [0, T]$ , with convergence rate

$$\sup_{t \in [0, T]} W_2(\rho_m(t), \rho_\infty(t)) \lesssim \frac{1}{m^{1/24}}.$$

## Corollary

*Since  $\rho_m(\cdot, t)$  converges to both  $\chi_{\Omega_t}$  and  $\rho_\infty(\cdot, t)$  as  $m \rightarrow \infty$ ,  $\chi_{\Omega_t}$  and  $\rho_\infty(\cdot, t)$  must be equal almost everywhere.*

- While the gradient flow approach cannot directly deal with general nonconvex bounded domains (with e.g. Neumann boundary conditions), the viscosity solution approach still applies and we have  $\rho_m \rightarrow \chi_{\Omega_t}$ .
- On the other hand, without the condition  $\Delta\Phi \geq 0$ , the gradient flow approach still works and we still have  $\rho_m(\cdot, t) \rightarrow \rho_\infty(\cdot, t)$  but the characterization of the modified velocity remains open.

# $\rho_m \rightarrow \chi_{\Omega_t}$ : Heuristics

First let us discuss the convergence of  $\rho_m$  to  $\chi_{\Omega_t}$ . The following heuristics suggest that  $\rho_m(\cdot, t)$  should converge to  $\chi_{\Omega_t}$  as  $m \rightarrow \infty$ . The main trick is to consider the limit of the corresponding pressure variable  $p_m = \frac{m}{m-1} \rho_m^{m-1}$  rather than  $\rho_m$ , which remains continuous as  $m \rightarrow \infty$ .

The equation for  $p_m$  is

$$(\rho_m)_t - \nabla \cdot (\rho_m (\nabla p_m + \nabla \Phi)) = 0$$

One then considers the corresponding PDE for  $p_m$ , and show the convergence of  $p_m$  to  $p$  by barrier (viscosity solutions) argument.

# Convergence of $\rho_m, p_m$ as $m \rightarrow \infty$ : Relevant work

- When  $\Phi = 0$  but with source term, in the patch case: Gil and Quirós (1998), K(2003).
- Weak solutions theory is developed for general initial data in Perthame-Quiros-Vazquez (2013), where they study the  $m \rightarrow \infty$  limit of

$$\rho_t - \Delta(\rho^m) = \rho G(p).$$

- We first define viscosity solution for (FB), and prove the comparison principle.
- Then we construct the “lower limit” of  $\{p_m\}_m$  as  $m \rightarrow \infty$ :

$$u_2(x, t) := \lim_{n \rightarrow \infty} \inf_{\substack{m \geq n \\ |(x,t) - (y,s)| < 1/n}} p_m(y, s),$$

and use comparison arguments to show that  $u_2$  is a supersolution of the Hele-Shaw problem ( $P$ ) with the initial pressure satisfying  $\{p_0 > 0\} = \Omega_0$ .



$$\rho_m \rightarrow \chi_{\Omega_t}$$

Roughly speaking, the strategy is then to show that the corresponding “upper limit”  $u_1$  of  $\{\rho_m\}_m$  is a subsolution of (P) with the initial data  $\rho_0$ . Then due to the comparison principle we can conclude that  $u_1 \leq (u_2)^*$ .

Since  $u_1 \geq u_2$  by definition, it follows that  $u_1 = (u_2)^*$  and  $(u_1)_* = u_2$ . Let  $\Omega_t := \{u_1(\cdot, t) > 0\}$ . Then  $(\overline{\Omega_t})^0 = (\Omega_t)^0$  and  $\rho_m$  uniformly converges to  $\chi_{\Omega_t}$  away from  $\partial\Omega_t$  with initial data  $u_0 = \chi_{\Omega_0}$ .

# $\rho_m \rightarrow \rho_\infty$ : based on the JKO scheme

Next we proceed to show  $\rho_m \rightarrow \rho_\infty$ . The goal is to show

$$W_2(\rho_m, \rho_\infty) \leq Cm^{-1/24},$$

where  $W_2$  is the 2-Wasserstein distance.

To this end, let us first compare discrete-time solutions over one time step. Let  $\mu_m$  and  $\mu_\infty$  be the respective minimizer of the following JKO scheme for one time step:

$$\mu_m = \operatorname{argmin}_{\rho \in \mathcal{P}_2(\mathbb{R}^d)} E_m[\rho] + \frac{1}{2\Delta t} W_2^2(\rho, \rho_0)$$

$$\mu_\infty = \operatorname{argmin}_{\rho \in \mathcal{P}_2(\mathbb{R}^d)} E_\infty[\rho] + \frac{1}{2\Delta t} W_2^2(\rho, \rho_0)$$

We want to estimate  $W_2(\mu_m, \mu_\infty)$ : the main difficulty is that  $\mu_m$  may not be in  $L^\infty$ .

Towards a contradiction, suppose  $W_2(\mu_m, \mu_\infty)$  is large; in this case we want to find a better competitor  $\tilde{\mu}$ , such that

$$\begin{aligned} E_m[\tilde{\mu}] + \frac{1}{2\Delta t} W_2^2(\tilde{\mu}, \rho_0) + E_\infty[\tilde{\mu}] + \frac{1}{2\Delta t} W_2^2(\tilde{\mu}, \rho_0) \\ < E_m[\mu_m] + \frac{1}{2\Delta t} W_2^2(\mu_m, \rho_0) + E_\infty[\mu_\infty] + \frac{1}{2\Delta t} W_2^2(\mu_\infty, \rho_0) \end{aligned}$$

This means  $\tilde{\mu}$  would at least beat one of  $\mu_m$  and  $\mu_\infty$ !

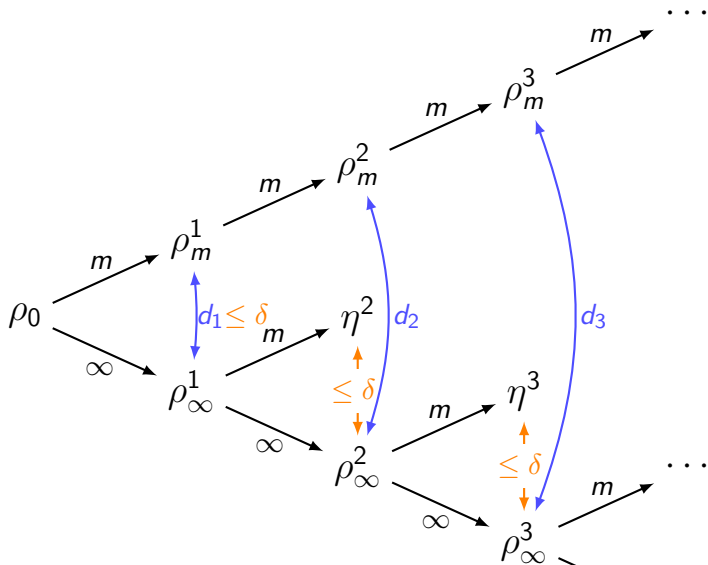
How do we find such  $\tilde{\mu}$ ?

- First guess: Choose  $\tilde{\mu}$  as the midpoint (along the generalized geodesics) of  $\mu_m$  and  $\mu_\infty$ . This choice saves the distance.
- But  $E_\infty[\tilde{\mu}]$  may be infinite.

A suitable competitor  $\tilde{\mu}$  can be found as follows:

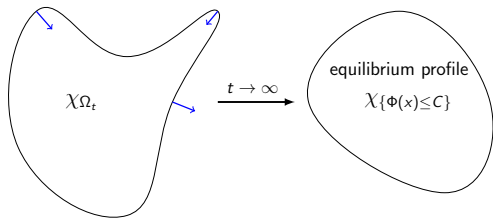
- 1 Even though the maximum density of  $\mu_m$  may exceed 1,  $\int (\mu_m - 1)_+ dx \lesssim m^{-1/2}$  for  $m > 2$ .
- 2 Thus we can find some  $\|\eta_m\|_\infty \leq 1$ , such that  $W_2(\eta_m, \mu_m) \lesssim m^{-1/4}$ , and  $E_m[\eta_m] \approx E_m[\mu_m]$ .
- 3 One can then choose  $\tilde{\mu}$  as the midpoint (along the generalized geodesics) of  $\eta_m$  and  $\mu_\infty$ . (Note that  $\|\tilde{\mu}\|_\infty \leq 1$ .)
- 4  $\tilde{\mu}$  would be better than either  $\mu_m$  or  $\mu_\infty$  if  $W_2(\mu_m, \mu_\infty) \gg m^{-1/8}$ .

# $\rho_m \rightarrow \rho_\infty$ : Controlling the distance for multiple time steps



# Confinement and long time behavior

- For  $1 < m \leq \infty$ , if  $\Phi(x) \rightarrow \infty$  as  $|x| \rightarrow \infty$ , using the comparison principle, we know that if the initial data is compactly supported, the discrete solution to JKO scheme will be uniformly confined for all time steps.
- If  $\Phi$  is strictly convex,  $\rho_\infty$  converges to the global minimizer (which is  $\chi_{\{\Phi(x) \leq C\}}$  for some  $C$ ) exponentially fast in  $W_2$  distance.



Many open questions remain. The ultimate goal would be to try to generalize the continuity equation with  $L_\infty$  constraint, possibly characterized as the singular limit of the porous medium equation with drift

$$\rho_t - \Delta(\rho^m) + \nabla \cdot (\vec{v}\rho) = 0.$$

as  $m \rightarrow \infty$ .

## Part II: Aggregation with Height constraint

Next we discuss a different but relevant problem, which can be formally viewed as the singular limit of Patlak-Keller-Segel (PKS) equation:

$$\rho_t - \Delta(\rho^m) - \nabla \cdot (\rho \nabla(\rho * \mathcal{N})) = 0.$$

This is joint work with  
Katy Craig (UCLA) and Yao Yao (UW Madison).



- Let  $\rho_\infty(\cdot, t)$  be the gradient flow of

$$\tilde{E}_\infty[\rho] = \begin{cases} \int_{\mathbb{R}^2} \rho(\rho * \mathcal{N}) dx & \text{for } \|\rho\|_\infty \leq 1 \\ +\infty & \text{otherwise} \end{cases}$$

where  $\mathcal{N}$  is the Newtonian potential.

- Uniqueness of the minimizer follows from certain convexity properties of  $\tilde{E}_\infty$  given by Carrillo, Lisini and Mainini (2012). The stability of the JKO scheme is much weaker due to the weak convexity properties of the energy  $\tilde{E}_\infty$ .

## Open questions:

- Does the discrete-time solutions converge to a gradient flow solution in a stable way?
- Can one characterize the corresponding gradient flow solution?
- As  $t \rightarrow \infty$ , does  $\rho_\infty$  eventually converge to the characteristic function of a ball? **yes if  $n=2$**
- Does the solutions of (PKS) converge to  $\rho_\infty$  as  $m \rightarrow \infty$ ?

**Open**

To show the convergence of discrete-time scheme with  $E_\infty$ , we recall the notion of  $\omega$ -convexity:

## Definition (Carrillo-Lisini-Mainini)

$E$  is called  $\omega$ -convex if for  $\rho_0, \rho_1 \in \mathcal{P}_{2,ac}(\mathbb{R}^d)$  we have

$$E(\rho_t) \leq (1-t)E(\rho_0) + tE(\rho_1) \\ + C[(1-t)\omega(t^2 W_2^2(\rho_0, \rho_1)) + t\omega((1-t)^2 W_2^2(\rho_0, \rho_1))],$$

where  $\omega(x) = x|\ln x|$  for small  $x$ .

# Contraction Inequality for $\omega$ -convex energy

We then have the following contraction inequality.

## Theorem ( K. Craig)

- $\tilde{E}_\infty$  is  $\omega$ -convex.
- Suppose  $E$  is  $\omega$ -convex, then the corresponding solutions of the JKO scheme satisfies

$$f_\tau(W_2(\mu_\tau, \nu_\tau)) \leq W_2^2(\mu_0, \nu_0) + C\tau^2 \ln \tau,$$

where  $f_\tau(x) = x - C\tau\omega(x)$ .

Based on above inequality, one can follow the argument of Crandall-Liggett to obtain a recursive inequality to estimate  $W_2(\mu_\tau, \nu_h)$ , and thus to show that JKO scheme converges to a unique limit  $\rho_\infty$  in Wasserstein distance.

# Characterization of the gradient flow solution

Next we consider characterizing  $\rho_\infty$  with a free boundary problem. The corresponding approximating energy is

$$\tilde{E}_m(\rho) := \int \frac{1}{m} \rho^m + \rho \mathcal{N} * \rho,$$

But then we realize that the corresponding gradient flow of above energy is hard to analyze due to the lack of convexity properties of  $\tilde{E}_m$ .

The main difficulty lies in the lack of  $L^\infty$ -bound for the discrete-time gradient flow solutions. In fact it is open whether the discrete-time solutions converges to the continuum solutions of (PKS) in spite of their formal connection.

# Characterization of the gradient flow solution

Hence we will use instead the following energy

$$E_m(\rho) := \int \frac{1}{m} \rho^m + \rho \mathcal{N} * \rho_\infty,$$

which is  $\omega$ -convex, and show that the corresponding gradient flow solution  $\rho_m$  converges.

As before, we only consider the patch case, i.e. when  $\rho_0 = \chi_{\Omega_0}$ . Here the corresponding free boundary problem is:

$$(FB) \quad \begin{cases} -\Delta p = \Delta \Phi = 1 & \text{in } \{p(\cdot, t) > 0\} =: \Omega(t); \\ V = |Dp| - \partial_\nu \Phi & \text{on } \partial\Omega(t), \end{cases}$$

where  $\Phi = \chi_{\Omega(t)} * \mathcal{N}$ .

## Theorem (Craig-K-Yao)

$\rho_m$  converges to  $\rho_\infty = \chi_{\Omega(t)}$  where  $\Omega(t)$  solves (FB).

# Long time behavior of $\rho_\infty$

Using the free boundary formulation for  $\rho_\infty$ , we can show the following:

## Theorem (Craig-K-Yao)

*When  $n = 2$ ,  $\Omega_t$  converges to a ball as  $t \rightarrow \infty$ .*

We prove this by showing that the second moment  $\int \rho_\infty(x, t) |x|^2 dx$  decreases in time unless  $\rho_\infty = \chi_B$ .



# Computing the second moment

The evolution of  $M_2[\rho(t)]$  is given by

$$\begin{aligned}\frac{d}{dt}M_2[\rho(t)] &= - \int_{\mathbb{R}^2} \rho \nabla(\rho * \mathcal{N}) \cdot \vec{x} dx - \int_{\mathbb{R}^2} \rho \nabla p \cdot \vec{x} dx \\ &= - \frac{1}{2\pi} \int_{\mathbb{R}^2} \int_{\mathbb{R}^2} \rho(x)\rho(y) \frac{(\vec{x} - \vec{y}) \cdot \vec{x}}{|\mathbf{x} - \mathbf{y}|^2} dy dx - \int_{\Omega(t)} \nabla p \cdot \vec{x} dx \\ &= - \frac{1}{4\pi} \int_{\mathbb{R}^2} \int_{\mathbb{R}^2} \rho(x)\rho(y) dy dx + 2 \int_{\Omega(t)} p(x) dx \\ &= - \frac{1}{4\pi} |\Omega(t)|^2 + 2 \int_{\Omega(t)} p(x) dx.\end{aligned}$$

The quantity above is negative unless  $\Omega(t)$  is a ball due to [Talenti, 1976].

# References

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Thank you for your attention!